

208(4): Checking and Development of the Equation of Motion

First consider:

$$\begin{aligned}\frac{d}{dt} \left(\frac{\partial f}{\partial t} \right) &= \frac{1}{2} \frac{d}{dt} \left(\omega \frac{df}{d\theta} \right) \\ &= \frac{1}{2} \left(\left(\frac{d\omega}{dt} \right) \left(\frac{df}{d\theta} \right) + \omega \frac{d}{dt} \left(\frac{df}{d\theta} \right) \right) \quad - (1) \\ &= 0.\end{aligned}$$

Secondly consider:

$$F = \frac{\partial f}{\partial t} \quad - (2)$$

It is seen that:

$$F = F(r(t), \theta(t)) \quad - (3)$$

For example, for a hyperbolic spiral:

$$f = \theta^2 \quad - (4)$$

and $\theta = \theta(r, t) \quad - (5)$

From eq. (3), proceed as in note 207(8) to

find that: $\frac{\partial F}{\partial t} = \frac{1}{2} \omega \frac{dF}{d\theta} \quad - (6)$

so: $\frac{d}{dt} \left(\frac{\partial f}{\partial t} \right) = \frac{1}{2} \frac{d}{dt} \left(\omega \frac{d}{d\theta} \left(\frac{\partial f}{\partial t} \right) \right)$

$$\begin{aligned}
 &= \frac{1}{2} \omega \frac{d}{d\theta} \left(\frac{1}{2} \omega \frac{df}{d\theta} \right) \dots \\
 &= \frac{1}{4} \omega \frac{d}{d\theta} \left(\omega \frac{df}{d\theta} \right) = 0 \quad \text{--- (7)}
 \end{aligned}$$

From eqs. (1) and (7):

$$\boxed{\left(\frac{\partial \omega}{\partial t} \right) \left(\frac{df}{d\theta} \right) + \omega \frac{\partial}{\partial t} \left(\frac{df}{d\theta} \right) = \frac{1}{2} \omega \frac{d}{d\theta} \left(\omega \frac{df}{d\theta} \right)}$$

$$= 0 \quad \text{--- (8)}$$

The solutions of eq. (8) are:

$$\omega = 0 \quad \text{--- (9)}$$

and

$$\frac{d}{d\theta} \left(\omega \frac{df}{d\theta} \right) = 0 \quad \text{--- (10)}$$

so

$$\frac{d\omega}{d\theta} \frac{df}{d\theta} + \omega \frac{d^2 f}{d\theta^2} = 0 \quad \text{--- (11)}$$

$$\boxed{\frac{d\omega}{d\theta} = - \frac{\omega \frac{d^2 f}{d\theta^2}}{\frac{df}{d\theta}}} \quad \text{--- (12)}$$